#### **MA612L-Partial Differential Equations**

**Lecture 14: Reynolds Transport Theorem** 

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# Recap

#### **Reynolds Transport Theorem**



Consider the integration of  $\mathbf{f}=\mathbf{f}(\mathbf{x},t)$  over a time-dependent region  $\Omega(t)$  with boundary  $\partial\Omega(t)$ , then the Reynolds Transport theorem relates taking the derivative with respect to time as follows.

#### **Theorem 1 (Reynolds Transport Theorem)**

Let  $\Omega(t) \subset \mathbb{R}^3$  and  $\mathbf{f}: \Omega(t) \times [0,\infty) \to U$ , then

$$\frac{D}{Dt} \left( \int_{\Omega(t)} \mathbf{f} dV \right) = \int_{\Omega(t)} \frac{\partial \mathbf{f}}{\partial t} dV + \int_{\partial \Omega(t)} (\mathbf{v}.\mathbf{n}) \mathbf{f} dS$$
 (1)

Here  $\mathbf{x}(t)$  is the position of the points in  $\Omega(t)$ .  $\mathbf{n}(\mathbf{x},\mathbf{t})$  is the outward unit normal vector to  $\partial\Omega(t)$ . dV and dS are volume and surface elements at  $\mathbf{x}$ .  $\mathbf{v}(\mathbf{x},\mathbf{t})$  denotes the velocity of the area element. The function  $\mathbf{f}$  may be scalar-valued or vector-valued, or tensor-valued.  $\frac{D}{Dt}$  is usually called as total derivative or material derivative.

### **Reynolds Transport Theorem**



In fluid dynamics or continuum mechanics, this can be written as follows: Let  ${\bf B}$  be any property of the fluid and  $\beta=\frac{d{\bf B}}{dm}$  be the intensive value of  ${\bf B}$  (amount of  ${\bf B}$  per unit mass) in any small element of the fluid, then

$$\left(\frac{d\mathbf{B}}{dt}\right)_{\Omega(t)} = \int_{\Omega(t)} \left[\frac{\partial}{\partial t}(\rho\beta) + \mathbf{v}.\nabla(\rho\beta) + \rho\beta\nabla.\mathbf{v}\right] dV$$
 (2)

For the Pictorial Proof using fluid dynamics continuum mechanics approach, refer to the lecture notes of Hyunse Yoon, University of Iowa.



# **Conservation Laws**

#### **Conservation of Mass**



Use B=m in (2) then

$$\left(\frac{dm}{dt}\right)_{\Omega(t)} = 0, \ \beta = \left(\frac{dm}{dm}\right) = 1$$

$$\left(\frac{dm}{dt}\right)_{\Omega(t)} = \int_{\Omega(t)} \left[\frac{\partial}{\partial t}(\rho\beta) + \mathbf{v} \cdot \nabla(\rho\beta) + \rho\beta \nabla \cdot \mathbf{v}\right] dV$$

$$\implies 0 = \int \left[ \frac{\partial \rho}{\partial t} + \mathbf{v} \cdot \mathbf{\nabla}(\rho) + \rho \mathbf{\nabla} \cdot \mathbf{v} \right] dV$$

Hence

$$\frac{\partial \rho}{\partial t} + \nabla \cdot (\rho \mathbf{v}) = 0$$

(3)

#### **Conservation of Momentum**



Use  $B = m\mathbf{v}$  in (2) then

$$\left(\frac{dm\mathbf{v}}{dt}\right)_{\Omega(t)} = \int_{\Omega(t)} \mathbf{f} dV, \ \beta = \left(\frac{dm\mathbf{v}}{dm}\right) = \mathbf{v}$$

Here f is an external force.

$$\int_{\Omega(t)} \mathbf{f} dV = \int_{\Omega(t)} \left[ \frac{\partial}{\partial t} (\rho \mathbf{v}) + \mathbf{v} \cdot \nabla (\rho \mathbf{v}) + \rho \mathbf{v} \nabla \cdot \mathbf{v} \right] dV$$

$$\left| \frac{\partial}{\partial t} (\rho \mathbf{v}) + \mathbf{\nabla} \cdot (\rho \mathbf{v} \mathbf{v}) = \mathbf{\nabla} \cdot T_s + \mathbf{f}_b \right|$$

Here  $T_s = [(-p + \lambda \nabla \cdot \mathbf{v})I + 2\mu D], D = \frac{1}{2}(\nabla \mathbf{v} + \nabla \mathbf{v}^T)$ , p is the pressure,  $f_b$  is the body force and  $T_s$  is the stress tensor.

(4)

#### **Navier Stokes Equation**



$$\frac{\partial}{\partial t}(\rho \mathbf{v}) + \nabla \cdot (\rho \mathbf{v} \otimes \mathbf{v}) = -\nabla p + \mu \nabla^2 \mathbf{v} + \frac{1}{3}\mu \nabla (\nabla \cdot \mathbf{v}) + \rho \mathbf{g}$$
 (5)

The incompressible Navier-Stokes equation is given by

Inertia (per volume)
$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla)\mathbf{v} - \underbrace{\nu \nabla^2 \mathbf{v}}_{\text{Diffusion}} = \underbrace{-\nabla w}_{\text{Internal source}} + \underbrace{\mathbf{g}}_{\text{External source}}$$
(6)

## **Conservation of Energy**



Use  $B=E=m\left(u+\frac{1}{2}\mathbf{v}.\mathbf{v}\right)$  in (2) then

$$\left(\frac{dE}{dt}\right)_{\Omega(t)} = \dot{Q} - \dot{W}, \ \beta = \left(\frac{dE}{dm}\right) = e$$

$$\left| \frac{\partial}{\partial t} (\rho e) + \nabla \cdot (\rho \mathbf{v} e) = -\nabla \cdot \dot{q}_s - p \nabla \cdot \mathbf{v} + \nabla \cdot (\boldsymbol{\tau} \cdot \mathbf{v}) + \mathbf{f}_b \cdot \mathbf{v} + \dot{q}_v \right|$$
 (7)

Here p: pressure,  $\dot{q}_s$ : rate of heat transfer per unit area across the surface area,  $\dot{q}_v$ : rate of heat source or sink within material volume per unit volume,  $\dot{Q}$ : net rate of heat transferred to the material element,  $\dot{W}$ : net rate of work done by the material volume,  $\tau$ : viscous stress tensor

### **Heat Equation**



The conservation of total internal energy can be written as

$$\underbrace{\frac{\partial}{\partial t} \left( \rho \left[ e + \frac{1}{2} v^2 \right] \right)}_{\text{Rate of increase of Energy per unit volume}} + \underbrace{\nabla \cdot \left[ \rho \mathbf{v} \left( e + \frac{1}{2} v^2 \right) \right]}_{\text{Convection energy into point by flow}} = - \underbrace{\nabla \cdot \mathbf{q}}_{\text{net heat flux}} + \underbrace{\nabla \cdot (\sigma \cdot \mathbf{v})}_{\text{Work of Surface forces}} + \underbrace{\rho \mathbf{v} \cdot \mathbf{F}}_{\text{body forces}}$$
 (8)

$$\frac{\partial}{\partial t}(\rho c_p T) + \mathbf{v} \cdot \nabla T(T\mathbf{v}) = \nabla \cdot (k \nabla T) + \beta T \left( \frac{\partial p}{\partial t} + \mathbf{v} \cdot \nabla p \right) + \tau : \nabla \mathbf{v} + \mathbf{Q}$$
 (9)

Here  $c_p$ : specific heat capacity, k: thermal conductivity



# d'Alembert's Formula for Wave Equation

## **Recall: Transport Equation in** $\mathbb{R}^n \times (0, \infty)$



Consider the following inhomogeneous problem

$$\begin{cases} u_t + b.Du = f, \mathbf{x} \in \mathbb{R}^n, t > 0 \\ u(\mathbf{x}, 0) = g(\mathbf{x}), x \in \mathbb{R}^n \end{cases}$$

(10)

Then

$$u(\mathbf{x},t) = g(\mathbf{x} - \mathbf{b}t) + \int_{0}^{t} f(\mathbf{x} + (s-t)\mathbf{b}, s)ds, x \in \mathbb{R}^{n}, t \ge 0$$

solves the IVP (10).



Consider the following one-dimensional wave equation

$$\begin{cases} u_{tt} - c^2 u_{xx} = 0 & \text{in } \mathbb{R} \times (0, \infty) \\ u = f & \text{on } \mathbb{R} \times (t = 0) \\ u_t = g & \text{on } \mathbb{R} \times (t = 0) \end{cases}$$
(11)

Let us try to find the solution of the wave equation in terms of f and g. Let us rewrite the wave equation as follows:

$$\left(\frac{\partial}{\partial t} + c\frac{\partial}{\partial x}\right) \left(\frac{\partial}{\partial t} - c\frac{\partial}{\partial x}\right) u = u_{tt} - u_{xx} = 0$$



Let

$$v(x,t) = \left(\frac{\partial}{\partial t} - c\frac{\partial}{\partial x}\right)u(x,t)$$

Then the wave equation can be written as

$$v_t(x,t) + cv_x(x,t) = 0$$
 in  $\mathbb{R} \times (0,\infty)$ 

This is a simple transport equation. We know the solution to this problem, which is given by

$$v(x,t) = a(x - ct)$$

where

$$v(x,0) = a(x)$$



Therefore, we have

$$u_t(x,t) - cu_x(x,t) = a(x-ct)$$
 in  $\mathbb{R} \times (0,\infty)$ 

This is once again the transport equation. Therefore,

$$u(x,t) = f(x+ct) + \int_{0}^{t} a(x-cs-c(s-t))ds, x \in \mathbb{R}, t \ge 0$$

$$u(x,t) = f(x+ct) + \int_{0}^{t} a(x-2cs+ct))ds, x \in \mathbb{R}, t \ge 0$$



Use 
$$y = x - 2cs + ct$$
, then  $dy = -2cds$ ,  $s = 0 \implies y = x + ct$ ,  $s = t \implies y = x - ct$ 

$$u(x,t) = f(x+ct) + \frac{1}{2c} \int_{-\infty}^{\infty} a(y)dy, x \in \mathbb{R}, t \ge 0$$

Now,

$$a(x) = v(x,0) = u_t(x,0) - cu_x(x,0) = g(x) - cf'(x)$$

$$\implies \frac{1}{2c} \int_{x-ct}^{x+ct} a(y)dy = \frac{1}{2c} \int_{x-ct}^{x+ct} g(y)dy - \frac{1}{2} \int_{x-ct}^{x+ct} f'(y)dy$$

$$= \frac{1}{2c} \int_{x-ct}^{x+ct} g(y)dy - \frac{1}{2}f(x+ct) + \frac{1}{2}f(x-ct)$$



$$u(x,t) = \frac{1}{2} [f(x+ct) + f(x-ct)] + \frac{1}{2c} \int_{x-ct}^{x+ct} g(y)dy$$

is called d'Alembert's formula. This can be written as

$$u(x,t) = F(x+ct) + G(x-ct)$$

for appropriate F and G. Conversely, any function of this form solves  $u_{tt}-c^2u_{xx}=0$ . Observe the beauty of this equation, the general solution of the one-dimensional wave equation is a sum of the general solution of the transport equations

$$u_t + cu_x = 0$$
 and  $u_t - cu_x = 0$ 

## **Wave Equation: Separation Variables**



Recollect the solution obtained from the Separation of Variables. (Of course, this was on domain  $[0, L] \times (0, \infty)$ )

$$u(x,t) = \sum_{n=0}^{\infty} \left[ A_n \cos\left(\frac{cn\pi}{L}t\right) + B_n \sin\left(\frac{cn\pi}{L}t\right) \right] \sin\left(\frac{n\pi}{L}x\right)$$
 (12)

Using  $\sin(A \pm B) = \sin A \cos B \pm \cos A \sin B$  and  $\cos(A \pm B) = \cos A \cos B \mp \sin A \sin B$ , we can rewrite this as

$$u(x,t) = \frac{1}{2} \sum_{n=1}^{\infty} \left[ A_n \sin\left(\frac{n\pi}{L}(x+ct)\right) + A_n \sin\left(\frac{n\pi}{L}(x-ct)\right) \right]$$
$$+ \frac{1}{2} \sum_{n=1}^{\infty} \left[ B_n \cos\left(\frac{n\pi}{L}(x-ct)\right) - B_n \cos\left(\frac{n\pi}{L}(x+ct)\right) \right]$$



Again, you can see that

$$u(x,t) = F(x+ct) + G(x-ct)$$

When c=1,g is an odd function and f is an even function, then

$$u(0,t) = f(t)$$

When c = 1, g is an an even function and f is an odd function, then

$$u(0,t) = \int_{0}^{t} g(y)dy$$

When g=0, you can observe that the initial displacement splits into two parts, one moving to the right with speed c and the other to the left with speed c.



#### **Theorem 2**

Assume  $f \in C^2(\mathbb{R}), g \in C^1(\mathbb{R}), c=1$  and define u by d'Alembert's. Then,

- 1.  $u \in C^2(\mathbb{R} \times [0,\infty))$
- 2.  $u_{tt} u_{xx} = 0$  in  $\mathbb{R} \times [0, \infty)$
- 3.  $\lim_{\substack{(x,t)\to(x^0,0)\\t>0}} u(x,t) = f(x^0)$
- 4.  $\lim_{\substack{(x,t)\to(x^0,0)\\t>0}} u_t(x,t) = g(x^0)$

In (3) and (4) for each point  $x^0 \in \mathbb{R}$ 

The proof follows immediately from the above discussion and is left as an exercise.

#### Exercise



#### Exercise 1: CSIR-June-2019

Let u be the solution of (11) where c=1, f, g are in  $C^2(\mathbb{R})$  and satisfy the following conditions:

(1) 
$$f(x) = g(x) = 0$$
 for  $x \le 0$  (2)  $0 < f(x) \le 1$  for  $x > 0$ 

(1) 
$$f(x) = g(x) = 0$$
 for  $x \le 0$  (2)  $0 < f(x) \le 1$  for  $x > 0$  (3)  $g(x) > 0$  for  $x > 0$  (4)  $\int_{0}^{\infty} g(x) dx < \infty$ 

Then, which of the following statements are true? Justify your answer

- 1. u(x,t) = 0 for all x < 0 and t > 0
- 2. u is bounded on  $\mathbb{R} \times (0, \infty)$
- 3. u(x,t) = 0 whenever x + t < 0
- 4. u(x,t) = 0 for some (x,t) satisfying x + t > 0



Let us consider the following wave equation on the half-line  $\mathbb{R}_+$ . Note c=1 here.

$$\begin{cases} u_{tt} - u_{xx} = 0 & \text{in } \mathbb{R}_{+} \times (0, \infty) \\ u = f & \text{on } \mathbb{R}_{+} \times \{t = 0\} \\ u_{t} = g & \text{on } \mathbb{R}_{+} \times \{t = 0\} \\ u = 0 & \text{on } \{x = 0\} \times (0, \infty) \end{cases}$$
(13)

where f and g are given, with f(0) = g(0) = 0.



Let us convert (13) by extending u,g,h to all  $\mathbb R$  by **odd reflection**. That is, we set

$$\tilde{u}(x,t) := \begin{cases} u(x,t) & (x \ge 0, t \ge 0) \\ -u(-x,t) & (x \le 0, t \ge 0) \end{cases}$$

$$\tilde{f}(x) := \begin{cases} f(x) & (x \ge 0) \\ -f(-x) & (x \le 0) \end{cases}$$

$$\tilde{g}(x) := \begin{cases} g(x) & (x \ge 0) \\ -g(-x) & (x \le 0) \end{cases}$$



Then (13) becomes

$$\begin{cases} \tilde{u}_{tt} - \tilde{u}_{xx} = 0 & \text{in } \mathbb{R} \times (0, \infty) \\ \tilde{u} = \tilde{f} & \text{on } \mathbb{R} \times \{t = 0\} \\ \tilde{u}_{t} = \tilde{g} & \text{on } \mathbb{R} \times \{t = 0\} \end{cases}$$
(14)

Hence d'Alembert's formula becomes

$$\tilde{u}(x,t) = \frac{1}{2} [\tilde{f}(x+t) + \tilde{f}(x-t)] + \frac{1}{2} \int_{x-t}^{x+t} \tilde{g}(y) dy$$
 (15)



The solution obtained from the reflection method for (13) becomes

$$u(x,t) = \begin{cases} \frac{1}{2} [f(x+t) + f(x-t)] + \frac{1}{2} \int_{x-t}^{x+t} g(y) dy, & \text{if } x \ge t \ge 0\\ \frac{1}{2} [f(x+t) - f(t-x)] + \frac{1}{2} \int_{-x+t}^{x+t} g(y) dy, & \text{if } 0 \le x \le t \end{cases}$$
 (16)

- 1. If  $g \equiv 0$ , we can understand the formula (16) as saying that an initial displacement f splits into two parts. One moving to the right with speed one and another moving to the left with speed one
- 2. The latter reflects off the point x=0, where the vibrating string is held fixed.

# **Thanks**

**Doubts and Suggestions** 

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