### **MA612L-Partial Differential Equations**

Lecture 36: Nonlinear PDE - Characteristic ODE

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Consider the nonlinear first-order PDE

$$F(Du, u, x) = 0$$
 in  $\Omega$  (1)

subject to the boundary condition

$$u = g$$
 on  $\Gamma$  (2)

As we have seen in Jacobi's method, we generalize this concept as follows: Suppose u solves (1) and (2). Fix  $\mathbf{x} \in \Omega$ . We would like to calculate  $u(\mathbf{x})$  by finding some curve lying within  $\Omega$  connecting  $\mathbf{x}$  with a point  $\mathbf{x}^0 \in \Gamma$ .



Suppose, we can describe  ${\bf x}$  parametrically as follows:

$$\mathbf{x}(s) = (x_1(s), x_2(s), \dots, x_n(s)), s \in \mathbb{R}$$
 (3)

Assume that  $u \in C^2$  is a solution of (1). Define

$$z(s) := u(\mathbf{x}(s)) \tag{4}$$

and

$$\mathbf{p}(s) := Du(\mathbf{x}(s)) = (p_1(s), p_2(s), \cdots, p_n(s)) = (u_{x_1}(s), u_{x_2}(s), \cdots, u_{x_n}(s))$$
(5)

Here z gives the values of u along the curve and  $\mathbf{p}$  gives the values of the gradient Du. Now, we must choose x in such a way that we can compute z and  $\mathbf{p}$ .



If we differentiate (5) w.r.t. s, we get

$$\frac{dp_i}{ds} = \sum_{i=1}^{n} \frac{\partial^2 u}{\partial x_i \partial x_j} (\mathbf{x}(s)) \frac{dx_j}{ds}$$
 (6)

Similarly differentiating (1) w.r.t.  $x_i$ , we obtain

$$\sum_{j=1}^{n} \frac{\partial F}{\partial p_{j}}(Du, u, \mathbf{x}) \frac{\partial^{2} u}{\partial x_{j} \partial x_{i}} + \frac{\partial F}{\partial z}(Du, u, \mathbf{x}) \frac{\partial u}{\partial x_{i}} + \frac{\partial F}{\partial x_{i}}(Du, u, \mathbf{x}) = 0$$
 (7)

Now, choose your x(s) such that

$$\frac{dx_j}{ds}(s) = \frac{\partial F}{\partial p_j}(\mathbf{p}(s), z(s), \mathbf{x}(s)) \tag{8}$$



Hence, we obtain

$$\sum_{j=1}^{n} \frac{\partial F}{\partial p_{j}}(\mathbf{p}(s), z(s), \mathbf{x}(s)) \frac{\partial^{2} u}{\partial x_{j} \partial x_{i}}(\mathbf{x}(s)) + \frac{\partial F}{\partial z}(\mathbf{p}(s), z(s), \mathbf{x}(s)) p_{i}(s) + \frac{\partial F}{\partial x_{i}}(\mathbf{p}(s), z(s), \mathbf{x}(s)) = 0$$

Using the above expression and (8) in (6), we obtain that

$$\frac{dp_i}{ds} = -\frac{\partial F}{\partial z}(\mathbf{p}(s), z(s), \mathbf{x}(s))p_i(s) - \frac{\partial F}{\partial x_i}(\mathbf{p}(s), z(s), \mathbf{x}(s))$$
(9)



Again differentiating (4) w.r.t. s, we obtain

$$\frac{dz}{ds} = \sum_{j=1}^{n} \frac{\partial u}{\partial x_j}(\mathbf{x}(s)) \frac{dx_j}{ds} = \sum_{j=1}^{n} p_j(s) \frac{\partial F}{\partial p_j}(\mathbf{p}(s), z(s), \mathbf{x}(s))$$
(10)

Hence we obtain

$$\begin{cases} (a) & \dot{\mathbf{p}}(s) = -D_x F(\mathbf{p}(s), z(s), \mathbf{x}(s)) - D_z F(\mathbf{p}(s), z(s), \mathbf{x}(s)) \mathbf{p}(s) \\ (b) & \dot{z}(s) = D_p F(\mathbf{p}(s), z(s), \mathbf{x}(s)) . \mathbf{p}(s) \\ (c) & \dot{\mathbf{x}}(s) = D_p F(\mathbf{p}(s), z(s), \mathbf{x}(s)) \end{cases}$$
(11)



- 1. These 2n + 1 first-order ODEs are called characteristic equations of the nonlinear PDE (1).
- 2. The functions (5) and (4) are called characteristics.
- 3. We refer  $\mathbf{x}(s)$  as the projected characteristic.
- 4. The projection of the full characteristics  $(\mathbf{p}(.), z(.), \mathbf{x}(.)) \subset \mathbb{R}^{2n+1}$  onto the physical region  $\Omega \subset \mathbb{R}^n$

#### **Theorem 1**

Let  $u\in C^2(\Omega)$  solve the nonlinear first order PDE (1) in  $\Omega$ . Assume  $\mathbf{x}(.)$  solves the ODE (11)(c). Then  $\mathbf{p}(.)$  solve the ODE (11)(a) and z(.) solve the ODE (11)(b) for those s such that  $x(s)\in\Omega$ .

### **Characteristic ODE: F linear**



Let us consider the linear PDE and homogeneous, then

$$F(Du, u, \mathbf{x}) = \mathbf{b}(\mathbf{x}).Du(\mathbf{x}) + c(\mathbf{x})u(\mathbf{x}) = 0$$

Then

$$F(\mathbf{p}, z, \mathbf{x}) = \mathbf{b}(\mathbf{x}) \cdot \mathbf{p} + c(\mathbf{x})z$$

Hence

$$D_{\mathbf{p}}F = \mathbf{b}(\mathbf{x})$$

and

$$\begin{cases} (b) & \dot{z}(s) = \mathbf{b}(\mathbf{x}(s)).\mathbf{p}(s) = -c(\mathbf{x}(s))z(s) \\ (c) & \dot{\mathbf{x}}(s) = \mathbf{b}(\mathbf{x}(s)) \end{cases}$$

Here,  $\mathbf{p}(.)$  is not needed.

(13)

(12)

### **Characteristic ODE: F linear**



#### **Example 2**

Solve the following PDE

$$\begin{cases} x_1 u_{x_2} - x_2 u_{x_1} = u & \text{in } \Omega \\ u = g & \text{on } \Gamma \end{cases}$$
 (14)

where  $\Omega=\{x_1>0,x_2>0\},\Gamma=\{x_1>0,x_2=0\}\subset\partial\Omega.$  This PDE is of the form linear PDE, with  $\mathbf{b}=(-x_2,x_1)$  and c=-1. Thus, the equation will become

$$\begin{cases} (b) & \dot{z}(s) = z \\ (c) & \dot{x_1} = -x_2, \dot{x_2} = x_1 \end{cases}$$
 (15)

### **Characteristic ODE: F linear**



Upon solving, we obtain

$$\begin{cases} (b) & z(s) = z_0 e^s = g(x_0) e^s \\ (c) & x_1(s) = x_0 \cos s, x_2(s) = x_0 \sin s \end{cases}$$
 (16)

where  $x_0 \geq 0, 0 \leq s \leq \frac{\pi}{2}$ . Fix a point  $(x_1, x_2) \in \Omega$ . Let  $s > 0, x_0 > 0$  such that  $(x_1, x_2) = (x_0 \cos s, x_0 \sin s)$ . That is,  $x_0 = \sqrt{x_1^2 + x_2^2}, s = \tan^{-1}\left(\frac{x_2}{x_1}\right)$ . Hence

$$u(x_1, x_2) = g\left(\sqrt{x_1^2 + x_2^2}\right) e^{\tan^{-1}\left(\frac{x_2}{x_1}\right)}$$

## **Characteristic ODE: F Quasilinear**



Let us consider the quasilinear PDE and homogeneous, then

$$F(Du, u, \mathbf{x}) = \mathbf{b}(\mathbf{x}, u(\mathbf{x})).Du(\mathbf{x}) + c(\mathbf{x}, u(\mathbf{x})) = 0$$

Then

$$F(\mathbf{p}, z, \mathbf{x}) = \mathbf{b}(\mathbf{x}, z) \cdot \mathbf{p} + c(\mathbf{x}, z)$$

Hence

$$D_{\mathbf{p}}F = \mathbf{b}(\mathbf{x}, z)$$

and

$$\begin{cases} (b) & \dot{z}(s) = \mathbf{b}(\mathbf{x}(s), z(s)).\mathbf{p}(s) = -c(\mathbf{x}(s), z(s)) \\ (c) & \dot{\mathbf{x}}(s) = \mathbf{b}(\mathbf{x}(s), z(s)) \end{cases}$$

(18)

(17)

Here,  $\mathbf{p}(.)$  is not needed.

### **Characteristic ODE: F Quasilinear**



#### Example 3

Solve the following PDE

$$\begin{cases} u_{x_1} + u_{x_2} = u^2 & \text{in } \Omega \\ u = g & \text{on } \Gamma \end{cases}$$
 (19)

where  $\Omega=\{x_2>0\}, \Gamma=\{x_2=0\}=\partial\Omega$ . This PDE is of the form quasilinear PDE, with  $\mathbf{b}=(1,1)$  and  $c=-z^2$ . Thus the equation will become

$$\begin{cases} (b) & \dot{z}(s) = z^2 \\ (c) & \dot{x_1} = 1, \dot{x_2} = 1 \end{cases}$$
 (20)

### **Characteristic ODE: F Quasilinear**



Upon solving, we obtain

$$\begin{cases} (b) & z(s) = \frac{z_0}{1 - sz_0} = \frac{g(x_0)}{1 - sg(x_0)} \\ (c) & x_1(s) = x_0 + s, x_2(s) = s \end{cases}$$
 (21)

where  $x_0\in\mathbb{R},s\geq 0$ . Fix a point  $(x_1,x_2)\in\Omega$ . Let  $s>0,x_0>0$  such that  $(x_1,x_2)=(x_0+s,s)$ . That is,  $x_0=x_1-x_2,s=x_2$ . Hence

$$u(x_1, x_2) = \frac{g(x_0)}{1 - sg(x_0)} = \frac{g(x_1 - x_2)}{1 - x_2 g(x_1 - x_2)}$$

# **Characteristic ODE: F Fully nonlinear**



#### **Example 4**

Solve the following PDE

$$\begin{cases} u_{x_1}u_{x_2} = u & \text{in } \Omega \\ u = x_2^2 & \text{on } \Gamma \end{cases}$$
 (22)

where  $\Omega = \{x_1 > 0\}, \Gamma = \{x_1 = 0\} = \partial \Omega$ . Here

$$F(\mathbf{p}, z, \mathbf{x}) = p_1 p_2 - z$$

.

$$\begin{cases} (a) & \dot{p}_1 = p_1, \dot{p}_2 = p_2 \\ (b) & \dot{z}(s) = 2p_1p_2 \\ (c) & \dot{x}_1 = p_2, \dot{x}_2 = p_1 \end{cases}$$

## **Characteristic ODE: F Fully nonlinear**



Upon solving, we obtain

$$\begin{cases} (a) & p_1(s) = \frac{x_0}{2}e^s, p_2(s) = 2x_0e^s \\ (b) & z(s) = x_0^2e^{2s} \\ (c) & x_1(s) = 2x_0(e^s - 1), x_2(s) = \frac{x_0}{2}(e^s + 1) \end{cases}$$
(24)

Fix a point  $(x_1, x_2) \in \Omega$ . Let  $s > 0, x_0 > 0$  such that

$$(x_1,x_2)=(2x_0(e^s-1),\frac{x_0}{2}(e^s+1)).$$
 That is,  $x_0=\frac{1}{4}(4x_2-x_1),e^s=\frac{x_1+4x_2}{4x_2-x_1}.$ 

Hence

$$u(x_1, x_2) = x_0^2 e^{2s} = \frac{(x_1 + 4x_2)^2}{16}$$

# **Thanks**

**Doubts and Suggestions** 

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